



Sequential Recommendation in Online Games with Multiple Sequences, Tasks and User Levels

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ABSTRACT

Online gaming is growing faster than ever before, with increasing challenges of providing better user experience. Recommender systems (RS) for online games face unique challenges since they must fulfill players' distinct desires, at different user levels, based on their action sequences of various action types. Although many sequential RS already exist, they are mainly single-sequence, single-task, and single-user-level. In this paper, we introduce a new sequential recommendation model for multiple sequences, multiple tasks, and multiple user levels (abbreviated as $M^3\text{Rec}$) in Tencent Games platform, which can fully utilize complex data in online games. We leverage Graph Neural Network and multi-task learning to design $M^3\text{Rec}$ in order to model the complex information in the heterogeneous sequential recommendation scenario of Tencent Games. We verify the effectiveness of $M^3\text{Rec}$ on three online games of Tencent Games platform, in both offline and online evaluations. The results show that $M^3\text{Rec}$ successfully addresses the challenges of recommendation in online games, and it generates superior recommendations compared with state-of-the-art sequential recommendation approaches.

CCS CONCEPTS

• Information systems → Recommender systems.

KEYWORDS

online games, sequential recommender systems, multi-task learning, graph neural network

*Work done when the first author was an intern in Tencent.

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1 INTRODUCTION

As web services are ever-expanding, sequential data (e.g., users' click logs or user traveling history) become prevalent in Recommender Systems (RS) and therefore *Sequential Recommender Systems* (SRS) have attracted more and more attention [11, 35, 43]. Given users' historical behavior sequences, SRS aim at predicting his/her next action, e.g., the next point of interest (i.e., POI) to visit, or the next product he/she will buy. Unlike traditional RS which learn from the *two-way* user-item interactions, SRS model the *three-way* interaction among a user, an item he/she has selected and an item he/she will select next. One specific application of SRS is recommendation in online games which is growing faster than ever before, with increasing challenges of providing better user experience. In this paper, we study the sequential recommendation problem in *Tencent Games*¹ where the heterogeneous information makes it difficult for traditional SRS to fully model the sequential behaviors of users.

Although many SRS already exist [11, 35, 43], they are mainly single-sequence, single-task, and single-user-level (i.e., modeling individual user instead of user groups), i.e., *single-task learning at single-user level for single-sequence RS* ($S^3\text{Rec}$ for short). Figure 1a demonstrates an example of such SRS. The blue timeline indicates the purchase sequence, i.e., products that one user bought. The task is to recommend the next item to purchase for the user. As the previous items are related to video cameras, the next item is likely to be also related to video camera. Some recent methods consider more content features (e.g., temporal feature, text and item category) [17, 57] to enhance SRS's ability. Though heterogeneous information has been considered, these methods still model sequential behaviors based on a single sequence. Additional information is utilized as auxiliary data and incorporated into the single sequence to optimize for a single task, i.e., predicting the next item the user will interact with.

¹<https://game.qq.com>

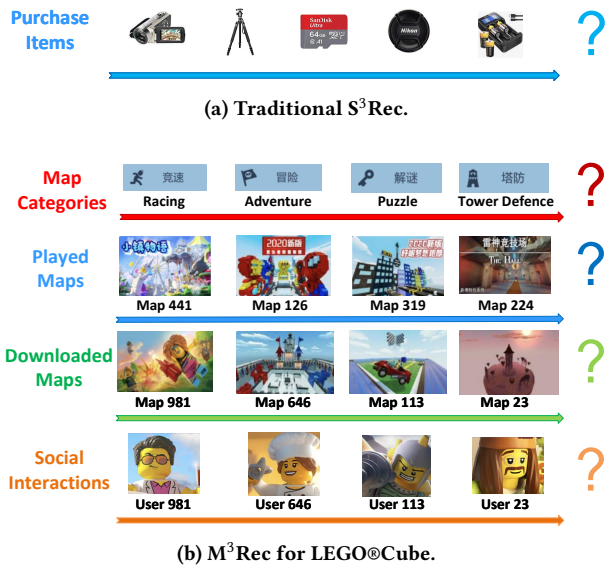


Figure 1: A comparison between traditional S³Rec and M³Rec for Tencent online game LEGO@Cube.

S³Rec is suitable for recommendation scenarios such as book or movie recommendation. However, the recommendation in online games faces unique challenges that S³Rec cannot handle well:

- Firstly, the action types are diverse in online gaming platforms. In other recommendation scenarios, such as book or movie recommendation, users can only adopt limited actions, e.g., purchase or click. However, in online games, players are able to adopt many types of actions. For example, Figure 1b depicts part of the recommendation scenario of the game LEGO@Cube² in Tencent Games platform, where heterogeneous information (e.g. map category, played maps, downloaded maps, and social interactions) is contained in *multiple user action sequences* and they have different meanings for the same user. Conventional SRS are unable to distinguish such differences.
- Secondly, there are multiple tasks to be fulfilled in online gaming platforms. In other recommendation scenarios, recommendation providers are only interested in the main action type, e.g., purchase. However, predicting the next item to purchase is not the only task in online games. For example, in LEGO@Cube, the *multiple tasks* of predicting next map to download, next map to play are all important for the game developer and publisher to efficiently allocate resource, improve user experience, and increase revenue.
- Finally, there is different representation levels for users and user groups in online gaming platforms. Most online games incorporate strong social factors that allow users to team up in battles and regions. Thus, in order to deliver more accurate recommendations, SRS for online games need to model not only single-level user representations (i.e., representations

for each single user) but also *multiple user-level* representations (i.e., representations for user groups). However, few existing works consider modeling user representations in sequential recommendation, as pointed out by Fang et al. [11].

The new challenges in SRS for Tencent Games and the limitations of previous SRS motivate us to propose a *sequential recommender system with multiple sequences, tasks and user levels* (abbreviated as M³Rec). We leverage Graph Neural Network (GNN) [67] and multi-task learning [70] to design a multi-sequence, multi-task and multi-level neural recommendation architecture for M³Rec to fully utilize the complex information in the heterogeneous sequential recommendation scenario of Tencent Games. More descriptions for the recommenders in Tencent Games are provided in Section 2.

In summary, the major contributions of this paper are:

- We identify and formally define a new multi-sequence, multi-task and multi-level sequential recommendation problem, which is a practical problem existing in online games of Tencent Games platform. To our best knowledge, we are first to study this problem in terms of sequential recommendation in online games.
- We propose a new framework M³Rec for sequential learning in the heterogeneous recommendation scenario. M³Rec has the capacity to model the complex meanings of multiple sequences beneath the surface.
- We adopt multi-task learning in M³Rec so that it is able to optimize several tasks in parallel.
- We evaluate M³Rec on real data of three online games in Tencent Games platform and verify the effectiveness of M³Rec for the traditional task of recommending next item in SRS. Meanwhile, M³Rec can offer suggestions for other prediction tasks in online games with high quality.

The rest of the paper is organized as follows: Section 2 gives an overview of the recommendation scenario in Tencent Games and formally defines the new recommendation problem. We illustrate our proposed method, M³Rec, in Section 3. In Section 4, we compare M³Rec with other state-of-the-art sequential recommendation algorithms and verify its effectiveness. Section 6 concludes our work.

2 SEQUENTIAL RECOMMENDER SYSTEM FOR LEGO@CUBE

In this section, we will give an overview of LEGO@Cube as an example to illustrate the recommendation scenario of online games in Tencent Games platform. Then, we will define the sequential recommendation problem for M³Rec in online games.

2.1 Overview of SRS for LEGO@Cube

LEGO@Cube is a popular sandbox game developed and operated by Tencent Games. It provides a virtual world comprised of different areas for Chinese mobile players. Players are encouraged to freely download area maps, explore these areas, construct with LEGO bricks, and get involved in various tasks with friends. As such, for each player, four behavior sequences are available: the *map sequence* containing game maps that each user has downloaded, the *type category* containing map categories of each user's downloaded

²<https://lgwx.qq.com>

maps, the *play sequence* containing game maps played by each player, and the *friend sequence* containing other users that each user has interacted with.

Figure 1b illustrates how the SRS in LEGO®Cube organizes the data of multiple sequences for one player:

- The green timeline contains the downloaded map sequence of this player. It corresponds to the main task, namely recommending the next map that the target player will download.
- The red timeline contains the map categories corresponding to maps in the green timeline. The task for this sequence is to predict the map category of the next map to be recommended. This task is helpful for game operation engineers when the information of some players is insufficient to make fine-grained recommendations and they can use the category recommendation instead of map recommendation.
- The blue timeline contains the played map sequence of this player. The auxiliary task for this sequence is to predict which map will be played by the player next. As maps must be firstly downloaded and then they can be played, this task is useful for distinguishing maps which players will play even without being recommended in the download sequence (i.e., main task) and maps that players will play after they get exposure via the recommendation. Game operation engineers may tune the recommendation priority for the latter in the main task so that they can be played.
- The orange timeline contains the user-user interaction sequence of this player. The auxiliary task for this sequence is to predict the next player that this player will interact with. The predication results of this sequence can help game operation engineers identify similar or relevant players, which is used as part of the input to the game player clustering in Section 3.3.

The meanings of the elements in each sequence are different under the surface. For example, one map appearing in green timeline indicates that the player has downloaded the map, but it is not the indication of his/her preferences. Since SRS in the game may push maps to players based on some strategies (e.g., advertising), it is possible that players will download some maps that he/she does not feel interesting actually. As a comparison, when a player played a map in blue timeline, the system can understand that it is a strong and explicit indication of his/her preferences. In summary, there are five recommendation problems which naturally arise from the sequences shown in Figure 1b:

- (1) **Next map prediction** is the main task that predicts which map will be downloaded by the user next.
- (2) **Next category prediction** is an auxiliary task that predicts which category of map will be downloaded by the user next.
- (3) **Next play prediction** is an auxiliary task that predicts which map will be played by the user next.
- (4) **Next friend prediction** is an auxiliary task that predicts who will be added to the user’s friend list next.
- (5) **Next group map prediction** is an auxiliary task that predicts the next download map for a user group.

The last task is related to a concept of *multiple user levels* in online games. Game operation engineers typically group users by group characters and sometimes promote game activities to some specific

user group. In this case, the recommendation is perform on the second user level, i.e., user group, instead of the first user level, i.e., individual player.

Different sequences in LEGO®Cube involve different meanings of players’ behaviors and simply incorporating them into one sequence without distinction will result in information loss. On the other hand, prediction tasks in LEGO®Cube vary in their goals and optimizing them simultaneously in one sequence and single user level is not straightforward. Therefore, previous sequential recommendation algorithms, which study single sequence, task and user level, cannot model the complex scenario in LEGO®Cube.

2.2 Problem Definition

We now first give the formal definition of the recommendation task of $S^3\text{Rec}$:

Definition 2.1 (Recommendation Task of $S^3\text{Rec}$). Let $I = \{i_1, \dots, i_{|I|}\}$ be a set of items. The action sequence s for a user is the sequence of items that the user has interacted with: $\{a_1, \dots, a_{|s|}\}$, where $a_j = \langle i_j, t_j \rangle$ indicates that the user selected item i_j at time t_j with $t_{|s|} \geq t_{|s|-1} \geq \dots \geq t_1$, and $|s|$ is the number of actions in s . Given an action sequence s , $S^3\text{Rec}$ predicts the item(s) that the user will next add to s . Items can be replaced by users or item categories if the sequence is related to user-user interactions or item information like categories.

We can extend Definition 2.1 and define the recommendation task of $M^3\text{Rec}$:

Definition 2.2 (Recommendation Task of $M^3\text{Rec}$). Let $I = \{i_1, \dots, i_{|I|}\}$ be a set of items. The action sequence set $\mathcal{S} = \{s_1, \dots, s_m\}$ for a user (or a user group) has m sequences (one main sequence and $m - 1$ auxiliary sequences) with possible different lengths. Each sequence s_q consists of items that the user (or user group) has interacted with: $\{a_1, \dots, a_{|s_q|}\}$, where $a_j = \langle i_j, o, t_j \rangle$ indicates that the user (or user group) performed action o on item i_j at time t_j , and $t_{|s_q|} \geq t_{|s_q|-1} \geq \dots \geq t_1$. Given \mathcal{S} , the main task of $M^3\text{Rec}$ is to predict the item in the next action that the user (or user group) will next add to the main sequence. Other auxiliary tasks aim at predicting the item/item category/user in the next action that the user (or user group) will next add to the auxiliary sequences.

Similar to $S^3\text{Rec}$, $M^3\text{Rec}$ does not predict the timestamp for the next action. Besides, the action type o is the same for all the actions in one sequence. Therefore, $M^3\text{Rec}$ does not need to predict the action type for new action.

3 $M^3\text{REC}$ FOR TENCENT GAMES PLATFORM

In this section, we will first review the Gated Graph Sequence Neural Network [29] based $S^3\text{Rec}$ [66] since $M^3\text{Rec}$ is built on the top of it. Then we will describe how $M^3\text{Rec}$ is able to model the sequential recommendation problem with multiple sequences, tasks and user level which is the scenario that online games in Tencent Games Platform have. Figure 2 provides an overview of $M^3\text{Rec}$.

3.1 GGS-NN Based $S^3\text{Rec}$

Li et al. [29] introduce the gate mechanism, which has been shown to be effective in Long Short-term Memory, into Graph Neural

Network (GNN) [48] and propose the Gated Graph Sequence Neural Network (GGS-NN) for modeling graphs as sequences. Later, Wu et al. [66] apply GGS-NN to S^3 Rec. In M^3 Rec, we use their design for the single-sequence, single-task and single-user-level recommendation unit in M^3 Rec, i.e., each of the tasks 1 to N in Figure 2.

Specifically, each user action sequence s can be viewed as a sequence graph \mathcal{G}_s and the update rule for the representation h_i of each node (i.e., item) i in s from epoch $t-1$ to epoch t using a GGS-NN layer can be defined as follows:

$$\begin{aligned} \mathbf{c}_{s,i}^{(t)} &= \mathbf{A}_{s,i}^T \left[\mathbf{h}_1^{(t-1)}, \dots, \mathbf{h}_n^{(t-1)} \right]^T + \mathbf{b} \\ \mathbf{z}_{s,i}^{(t)} &= \sigma(\mathbf{W}_z \mathbf{c}_{s,i}^{(t)} + \mathbf{V}_z \mathbf{h}_i^{(t-1)}) \\ \mathbf{r}_{s,i}^{(t)} &= \sigma(\mathbf{W}_r \mathbf{c}_{s,i}^{(t)} + \mathbf{V}_r \mathbf{h}_i^{(t-1)}) \\ \tilde{\mathbf{h}}_i^{(t)} &= \tanh(\mathbf{W}_h \mathbf{c}_{s,i}^{(t)} + \mathbf{V}_h (\mathbf{r}_{s,i}^{(t)} \odot \mathbf{h}_i^{(t-1)})) \\ \mathbf{h}_i^{(t)} &= (1 - \mathbf{z}_{s,i}^{(t)}) \odot \mathbf{h}_i^{(t-1)} + \mathbf{z}_{s,i}^{(t)} \odot \tilde{\mathbf{h}}_i^{(t)} \end{aligned} \quad (1)$$

where \mathbf{c} , \mathbf{z} , \mathbf{r} and $\tilde{\mathbf{h}}$ are gathering gate, reset gate, update gate, and candidate activation, respectively. $\sigma(\cdot)$ is the sigmoid function, \mathbf{h}_* is the vector representation of node in sequence s , “ \odot ” is the element-wise multiplication, and \mathbf{W}_* and \mathbf{V}_* are learnable matrices. $\mathbf{A}_s \in \mathbb{R}^{n_s \times 2n_s}$ is the connection matrix for s (i.e., the concatenation of outgoing adjacent matrix and ingoing adjacent matrix), and n_s indicates the number of unique nodes in s . $\mathbf{A}_{s,i} \in \mathbb{R}^{n_s \times 2}$ are the two columns of blocks in \mathbf{A}_s with respect to node i . For instance, Figure 3 illustrates an example showing the connection matrix for one user’s user-item interaction sequence $\{v_1, v_2, v_3, v_2, v_4\}$.

We may stack several GGS-NN layers to enhance the non-linearities of the model and we call it *GGS-NN unit* in the following. For one user’s user-item interaction sequence $\{v_1, \dots, v_l\}$ with l items in the sequence, the prediction for the next item is generated based on the local sequence embedding (i.e., the learned representation \mathbf{h}_l for the last node v_l in the sequence) and the global sequence embedding \mathbf{s}_g which is captured by a soft-attention layer:

$$\alpha_i = \mathbf{g}^T \sigma(\mathbf{W}_1 \mathbf{h}_l + \mathbf{W}_2 \mathbf{h}_i + \mathbf{c}), \quad \mathbf{s}_g = \sum_{i=1}^l \alpha_i \mathbf{h}_i \quad (2)$$

where \mathbf{g} , \mathbf{W}_1 and \mathbf{W}_2 are learnable weights. \mathbf{b} is the bias vector.

Finally, the predicted probability of an item j being the next item is:

$$\hat{r}_j = (\mathbf{W}_3 (\mathbf{s}_g \oplus \mathbf{h}_l))^T \mathbf{v}_j, \quad (3)$$

where \mathbf{v}_j is the embedding for the item j , \mathbf{W}_3 is a learnable weight matrix, and “ \oplus ” indicates the concatenation operation.

3.2 Modeling Multiple Sequences and Multi Tasks in M^3 Rec

Considering the multi-sequence and multi-task scenario that online games face, we choose to adopt multiple GGS-NN units for online games in Tencent Game platform. Each of them is used for a specific sequence and a specific task. Items in the original GGS-NN unit are replaced with item categories or users according to the task. For next category prediction task, a separate map category embedding layer is used instead of the item embedding layer.

As shown in Figure 3, each task is modeled using an independent GGS-NN unit with the soft-attention mechanism, and all tasks share the user embedding layer and item embedding layer. For instance, the same user i in the next map prediction task and the next friend prediction task of LEGO@Cube will share the same user embedding \mathbf{u}_i encoded by the shared user embedding layer. All the GGS-NN unit are trained together in the manner of multi-task learning. The details of the optimization will be illustrated in Section 3.4.

3.3 Modeling Multiple User Levels in M^3 Rec

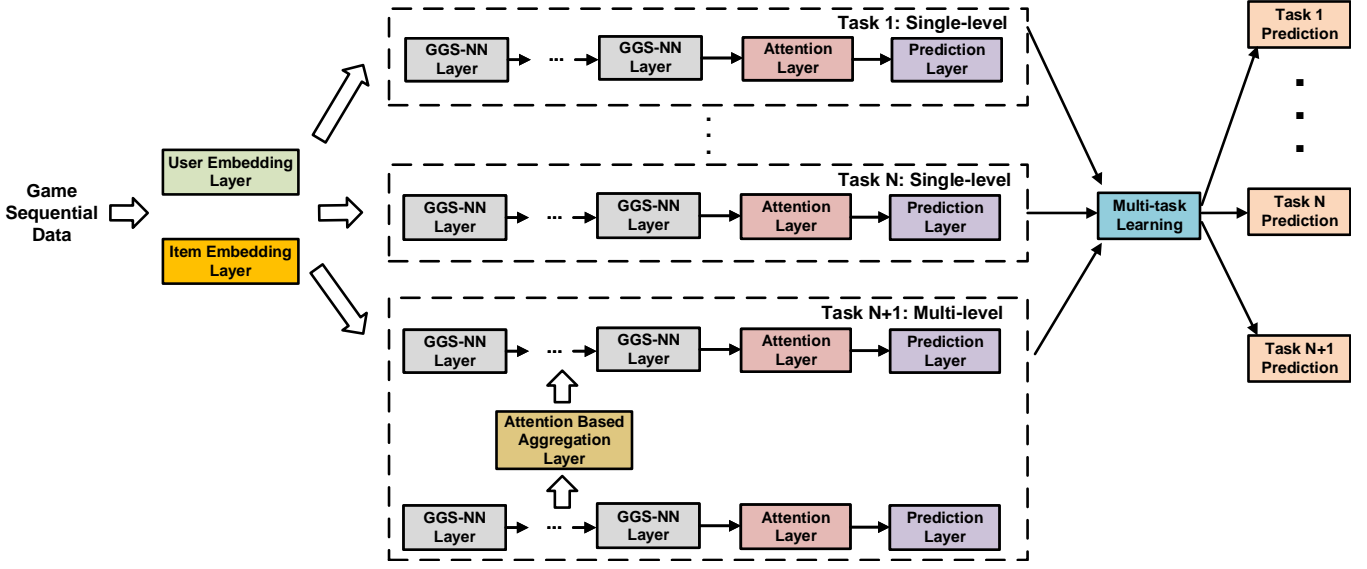
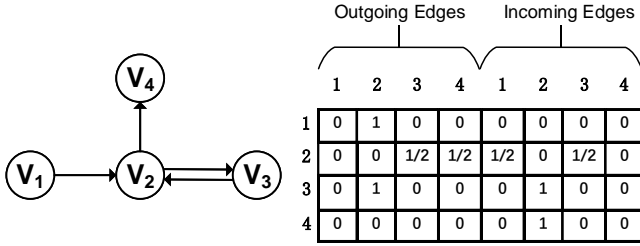
Game operation engineers lead game players to particular game activities for a better user experience, and a game activity typically has a target user group. Promoting game activities may increase the chance for users to see the maps they favor. Game players in LEGO@Cube have group characters, and operations engineers regularly update the user statistics. We run k-means clustering algorithm over these data to construct the player grouping information.

After identifying the player groups in the game, we are actually dealing with a classical problem in the recommender system community, namely *group recommendation* [2, 47], in the sequential recommendation task in Tencent Games platform. In traditional group recommendation task, the system aims at recommending items to a group of users that maximize the satisfaction of the group members, according to some semantics of group satisfaction. Users in the same group share some similarities (e.g., tastes or locations), and all members in the same group receive the same recommendation from the system. Group recommendation has been widely studied and applied in social recommenders (e.g., Shelfari [27]), event recommenders (e.g., Plancast [34]), restaurant recommenders (e.g., ZAGAT [39]), just to name a few. However, only a few studies [40, 54] has considered the group recommendation problem in sequential recommender.

We first define the *Hierarchical Multi-level Recommendation* for online games. Formally, we have a two-level recommendation architecture as shown in Task $N+1$ of Figure 2. On the bottom level, M^3 Rec conducts the general single-level sequential recommendation task, i.e., recommend an item to each individual game player. On the second level, M^3 Rec turns to *sequential group recommendation* task, i.e., recommend an item to groups of game players.

We design an attention based aggregation layer to aggregate the information from each group member at the bottom level and then construct the representation of the group on the second level. Recall that \mathbf{h}_i indicates the representation of item i . Suppose that \mathbf{q}_j is the representation of player j on the first level, \mathbf{p}_g is the representation of player group g at the bottom level, and $\mathcal{N}(g)$ indicates all the players that player group g contains. We aggregate the representations of individual players and generate the embedding for group g on the second level:

$$\begin{aligned} \mathbf{p}_g &= \text{RELU}(\mathbf{W}_p \sum_{i \in \mathcal{M}_g} \beta_i \mathbf{h}_i) \\ \beta_i &= \frac{\exp(\hat{\beta}_i)}{\sum_{i' \in \mathcal{N}(g)} \exp(\hat{\beta}_{i'})} \\ \hat{\beta}_i &= \mathbf{W}_b \mathbf{e}_i + b_e \\ \mathbf{e}_i &= \text{RELU}(\mathbf{W}_e \mathbf{h}_i + \mathbf{b}_e) \end{aligned} \quad (4)$$


 Figure 2: Overview of $M^3\text{Rec}$ for online games.

 Figure 3: An example of a sequence graph and the connection matrix A .

where $RELU(\cdot)$ is the Rectified Linear Unit, W_* is a weight matrix, b_e is a bias vector, and b_e is a bias term. In Equation 4, we assign different attention weight β to indicate the differing importance of each group member to the group. The attention weight β is parameterized with a single-layer feedforward neural network and then normalized by the softmax function. The motivation is that differences still exist among game players belonging to the same group, though players in the same group share very similar characteristics. Considering such nuances helps model the profile of the whole group better.

After obtaining the group representations p , the group recommendation process at the second level is similar to the process of GGS-NN based $S^3\text{Rec}$ illustrated in Section 3.1.

3.4 Optimization of Multi-task Learning

For each individual task, the predicted probability distribution for each possible item/item category/user being the next in an action sequence is similar to Equation 3:

$$\hat{r} = (W_3(s_g \oplus h_l))^T Q, \quad (5)$$

where Q is all the item embeddings, all the item category embeddings, or all the user embeddings, depending on the detailed task.

Then, the cross-entropy loss is used in the optimization for each task i :

$$\mathcal{L}_i = - \sum_{s \in \mathcal{S}_i} r_s \log(\hat{r}_s), \quad (6)$$

where \mathcal{S}_i is the interaction sequence set for task i , r_s indicates the one-hot encoding vector of the ground-truth next item/item category/user in the sequence s , and \hat{r}_s is calculated using Equation 5.

We use a common method to perform multi-task learning in $M^3\text{Rec}$, i.e., assign a task weight to each task loss and optimize the joint loss:

$$\mathcal{L} = \sum_{i=1}^t w_i \mathcal{L}_i, \quad (7)$$

where w_i is the task weight for task i . Stochastic gradient descent based methods can be used for the optimization and we use Adam [21] for $M^3\text{Rec}$.

4 EXPERIMENT

In this section, we move forward to evaluate the effectiveness of $M^3\text{Rec}$. We aim to answer the following questions:

- RQ1** How does each task contribute to $M^3\text{Rec}$'s performance?
- RQ2** How does $M^3\text{Rec}$ perform compared to the state-of-the-art methods in offline datasets?
- RQ3** How does $M^3\text{Rec}$ perform in online recommendation test?

4.1 Experimental Setup

We evaluate the performance of $M^3\text{Rec}$ and other competitors in three online games on Tencent Games platform. The first game is LEGO@Cube and we have illustrated the details of each sequences and each tasks in Section 2. We also select two popular Tencent games belonging to the Role Playing Game (RPG) genre. Both games allow players to team up and combat with each other. Players can

Table 1: Dataset statistics.

| Dataset | #sequence | #item/map | #user | #friend | #type |
|-----------|-----------|-----------|--------|---------|-------|
| LEGO@Cube | 1,884 | 2,446 | 20,319 | 18,435 | 7 |
| T-game | 60,811 | 62 | 75,518 | 14,707 | 12 |
| Y-game | 14,571 | 39 | 25,377 | 10,806 | 7 |

evolve their skills by purchasing items. We are required by our industry partners to anonymize the two games as Tgame and Ygame. For each player in Tgame, three behavior sequences are available: the *item sequence* each user has downloaded, the *type sequence* of each user’s downloaded item, and the *friend sequence* each user has interacted with. It presents three recommendation problems: i.e., *next item prediction*, *next type prediction* and *next friend prediction*. For each player in Ygame, five behavior sequences are available: the *item sequence*, the *type sequence*, the *friend sequence*, the *evolve sequence* of items each user has utilized to evolve his/her skills, and the *buy sequence* of items each user has bought. It presents four recommendation problems: i.e., *next item prediction*, *next type prediction* and *next friend prediction*. It present five recommendation problems: i.e., *next item prediction*, *next type prediction*, *next friend prediction*, *next evolution prediction* for the next item to be evolved and *next purchase prediction* for the next item to be bought.

The datasets used in our offline test are samples from the three games. We do not sample users whose behavior sequences are missing. For example, users do not interact with any friend will not be sampled. We show the statistics of datasets in Table 1. Note that, in LEGO@Cube, players acquire maps and in the rest two games players acquire items. In each dataset, the number of users who are friended is calculated based on users (1) whose behavior sequences are not sampled, and (2) who appear in the friend sequence of a sampled user sequence.

4.2 Evaluation Metrics in Offline Test

For the offline tests in Section 4.3 and Section 4.4, we evaluate experimental results based on three evaluation metrics in the top- n recommendations, namely Hit Ratio ($HR@n$), Mean Reciprocal Rank ($MRR@n$), and Normalized Discounted Cumulative Gain ($NDCG@n$). They are commonly adopted in evaluating recommendation performance [16, 32, 55, 66, 69].

4.3 Contributions of Multi-tasking (RQ1)

To understand how each task contribute to M^3Rec ’s performance (RQ1), we test three multi-task settings. We investigate the performance of modeling both main task *next map/item prediction* and one auxiliary tasks (i.e., *next type prediction* or *next friend prediction*), and the performance of modeling *all* three tasks. Note that here we only list three tasks that are common in all three games.

We compare different methods for $HR@n$, $MRR@n$, $NDCG@n$, where $n = 1, 2, \dots, 10$. We determine the top three results out of eight outcomes based on each evaluation metric in each dataset. Then we score each multi-task setting by calculating the percentage of top-3 results: $s_i = \frac{n_i}{N}$, where n_i is the number of times that results generated by the i -th multi-task setting are the best three results

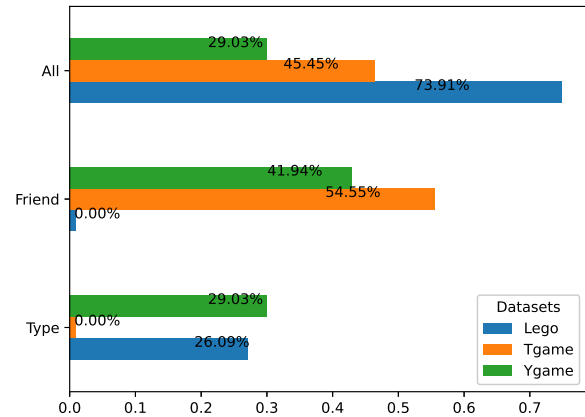


Figure 4: Percentage of top-3 results generated by different multi-tasking schemes.

based on any evaluation metric in any dataset. N is the overall number of top-3 results.

As shown in Figure 4, incorporating all auxiliary tasks generates the best results. It contributes to 29.03% of the top-3 results in Ygame, 45.45% of the top-3 results in Tgame and 73.91% of the top-3 results in LEGO@Cube. On the contrary, combining only one auxiliary task produces less stable results. For example, combining the main task with only next friend prediction does not perform well on LEGO@Cube. Its results are never among the top three best results in terms of any evaluation metric. Similarly, combining the main task with only next type prediction performs poorly on Tgame, with zero top three results in terms of any evaluation metric.

4.4 Offline Comparative Performance (RQ2)

To answer RQ2, we compare M^3Rec with the following methods as baselines in the offline test:

- GRU [55] is a state-of-the-art sequential recommendation model which applies Recurrent Neural Networks (RNN) with ranking-based loss functions. It improves [16] by data augmentation, and a method to account for shifts in the input data distribution.
- MARank [69] is recently proposed to unify both individual- and union-level item interaction into preference inference model from multiple views. It utilizes attention mechanism and residual neural network.
- STAMP [32] presents a novel short-term attention/memory priority model to capture users’ general interests from the long-term memory of a session context, whilst takes into account users’ current interests from the short-term memory of the last action.
- SR-GNN [66] models sequences as graph data and applies Gated Graph Neural Network [29] to extract complex transitions of items. An attention network is utilized to represent each sequence as a composition of global preference and current preference from the last action.

Table 2: Offline test on LEGO@Cube dataset with best results in bold.

| Method | HR@1 | HR@2 | HR@5 | HR@10 | MRR@2 | MRR@5 | MRR@10 | NDCG@2 | NDCG@5 | NDCG@10 |
|--------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| GRU | 0.0195 | 0.0357 | 0.0737 | 0.1356 | 0.0276 | 0.0378 | 0.0460 | 0.0357 | 0.0558 | 0.0770 |
| MARank | 0.0151 | 0.0329 | 0.0742 | 0.1311 | 0.0240 | 0.0350 | 0.0421 | 0.0329 | 0.0547 | 0.0737 |
| STAMP | 0.0184 | 0.0312 | 0.0725 | 0.1278 | 0.0248 | 0.0364 | 0.0434 | 0.0312 | 0.0539 | 0.0725 |
| SR-GNN | 0.0234 | 0.0379 | 0.0759 | 0.1088 | 0.0307 | 0.0402 | 0.0446 | 0.0379 | 0.0572 | 0.0684 |
| GAT | 0.0156 | 0.0335 | 0.0670 | 0.1328 | 0.0246 | 0.0334 | 0.0422 | 0.0335 | 0.0511 | 0.0737 |
| M ³ Rec | 0.0301 | 0.0513 | 0.0882 | 0.1423 | 0.0407 | 0.0505 | 0.0575 | 0.0513 | 0.0708 | 0.0891 |

Table 3: Offline test on Tgame dataset with best results in bold.

| | HR@1 | HR@2 | HR@5 | HR@10 | MRR@2 | MRR@5 | MRR@10 | NDCG@2 | NDCG@5 | NDCG@10 |
|--------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| GRU | 0.5317 | 0.6827 | 0.8544 | 0.9445 | 0.6072 | 0.6546 | 0.6670 | 0.6827 | 0.7760 | 0.8075 |
| MARank | 0.5012 | 0.6737 | 0.8532 | 0.9417 | 0.5874 | 0.6369 | 0.6491 | 0.6737 | 0.7710 | 0.8020 |
| STAMP | 0.4798 | 0.6531 | 0.8378 | 0.9337 | 0.5664 | 0.6175 | 0.6307 | 0.6531 | 0.7535 | 0.7870 |
| SR-GNN | 0.5327 | 0.6901 | 0.8601 | 0.9461 | 0.6114 | 0.6587 | 0.6705 | 0.6901 | 0.7830 | 0.8130 |
| GAT | 0.4029 | 0.6094 | 0.8238 | 0.9309 | 0.5061 | 0.5663 | 0.5810 | 0.6094 | 0.7273 | 0.7648 |
| M ³ Rec | 0.5328 | 0.6910 | 0.8605 | 0.9461 | 0.6115 | 0.6589 | 0.6706 | 0.6910 | 0.7834 | 0.8133 |

Table 4: Offline test on Ygame dataset with best results in bold.

| | HR@1 | HR@2 | HR@5 | HR@10 | MRR@2 | MRR@5 | MRR@10 | NDCG@2 | NDCG@5 | NDCG@10 |
|--------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| GRU | 0.5556 | 0.7266 | 0.9202 | 0.9882 | 0.6411 | 0.6943 | 0.7037 | 0.7266 | 0.8313 | 0.8552 |
| MARank | 0.5545 | 0.7230 | 0.9182 | 0.9863 | 0.6388 | 0.6926 | 0.7021 | 0.7230 | 0.8290 | 0.8528 |
| STAMP | 0.5200 | 0.6867 | 0.8931 | 0.9833 | 0.6034 | 0.6586 | 0.6714 | 0.6867 | 0.7962 | 0.8281 |
| SR-GNN | 0.5532 | 0.7305 | 0.9286 | 0.9904 | 0.6418 | 0.6966 | 0.7053 | 0.7305 | 0.8383 | 0.8602 |
| GAT | 0.4955 | 0.7031 | 0.9074 | 0.9822 | 0.5993 | 0.6575 | 0.6678 | 0.7031 | 0.8167 | 0.8430 |
| M ³ Rec | 0.5562 | 0.7380 | 0.9291 | 0.9895 | 0.6461 | 0.6987 | 0.7077 | 0.7380 | 0.8420 | 0.8634 |

Table 5: Online test on LEGO@Cube

| Method | NUV | CTR | ER | DR | CR |
|--------------------|------|-----------------|-----------------|-----------------|-----------------|
| M ³ Rec | 1.00 | 100.00% ± 3.09% | 100.00% ± 2.69% | 100.00% ± 2.28% | 100.00% ± 2.00% |
| IMF | 0.12 | 67.32% ± 7.32% | 70.29% ± 6.53% | 70.44% ± 5.61% | 71.41% ± 5.07% |
| SNS+IMF | 0.12 | 58.05% ± 6.83% | 66.58% ± 6.40% | 70.06% ± 5.61% | 67.79% ± 4.92% |
| RNN | 1.31 | 92.20% ± 2.60% | 96.16% ± 2.30% | 96.48% ± 2.00% | 95.08% ± 1.69% |
| HERec | 1.10 | 73.01% ± 2.44% | 75.29% ± 2.18% | 72.53% ± 1.90% | 72.71% ± 1.69% |
| oKNN | 5.46 | 77.56% ± 1.14% | 75.16% ± 1.02% | 75.38% ± 0.86% | 78.17% ± 0.77% |
| Random | 0.60 | 65.53% ± 3.25% | 44.56% ± 2.30% | 53.61% ± 2.19% | 58.42% ± 2.08% |

Table 6: Online test on Tgame

| Method | NUV | ARPU | CR(%) |
|--------------------|------|-------------|---------------|
| M ³ Rec | 1.00 | 1.00 ± 0.02 | 100.00 ± 1.05 |
| eALS | 0.95 | 0.84 ± 0.02 | 93.98 ± 1.10 |
| RF | 0.94 | 0.92 ± 0.02 | 91.31 ± 1.12 |
| IMF | 1.30 | 0.79 ± 0.02 | 82.96 ± 0.97 |
| Random | 0.93 | 0.21 ± 0.01 | 32.20 ± 0.94 |

Table 7: Online test on Ygame

| Method | NUV | ARPU | CR(%) |
|--------------------|------|-------------|----------------|
| M ³ Rec | 1.00 | 1.00 ± 0.46 | 100.00 ± 20.62 |
| IMF | 5.19 | 0.60 ± 0.13 | 68.33 ± 7.50 |
| POP | 3.05 | 0.19 ± 0.07 | 41.60 ± 7.65 |

- GAT [41] collaboratively considers the sequence order and the latent order of user preference by constructing a session graph and utilizing a weighted attention graph layer.

All methods, including competitors and M³Rec use an embedding size of 128, a learning rate of 0.0001 and a batch size of 128. For other special hyper-parameters of competitors, we use the recommended default settings given in their papers or open-source implementations.

The results of HR@ n , MRR@ n , and NDCG@ n with $n = 1, 2, 5, 10$ on the three datasets are shown in Tables 2, 3 and 4. We omit MRR@1 and NDCG@1 as these two are identical with HR@1. For M³Rec, the best performance multi-task setting is reported. We can observe that M³Rec performs consistently best in terms of all evaluation metrics on all datasets. This shows that M³Rec obtains very promising accuracy in the top- n sequential recommendations.

4.5 Online Comparative Performance (RQ3)

To validate that M³Rec has indeed promoted recommendation performance (RQ3), we conduct an online evaluation through a A/B test. We randomly select a group of exposed users for each recommendation approach (e.g., the competitors or M³Rec). Then we deliver top items with highest prediction score by each recommendation approach to the exposed users on the main task.

Competitors. Note that the competitors used in the online test are currently deployed in the online games. Due to various reasons such as security and efficiency, the recommender of each game might have differing models which are also different compared to those used in our offline test.

(1) Competitors on LEGO@Cube:

- IMF [19] is a latent factor model treating the data as positive and negative instances with vastly varying confidence levels.
- SNS+IMF improves IMF by leveraging the social network information. The confidence of each instance in the social network is computed by the efficient Personalized PageRank (PPR) algorithm on large graphs using the distributed computing framework [31].
- HERec [51] is a state-of-the-art recommendation model based on heterogeneous information network.
- RNN [16] deploys RNNs to predict next map.
- oKNN [5] is the online KNN algorithm, where each recommendation is made based on the majority voting from the user's cluster.
- Random is to randomly predict the next map.

(2) Competitors on Tgame.

- eALS [14] adopts an efficient element-wise Alternating Least Squares (eALS) learning technique in factorization machine [22] which weighs the missing data based on item popularity.
- RF [30] is the classic random forest prediction model.
- IMF [19] is the latent factor model which learns from weighted, positive and negative instances.
- Random is to randomly predict the next item.

- (3) **Competitors on Ygame** include IMF as used in the other two games and POP which is to give the most popular item as the prediction for the next item.

Evaluation Metrics. The evaluation metrics are suggested by the operation team in Tencent game, which are designed for each game in the purpose of better operation. The following evaluation metrics are based on UV , which is the number of users exposed in each group:

(1) Evaluation Metrics for LEGO@Cube:

- Click Through Rate (CTR) is calculated as $CTR = C/UV$, where C is the total clicks received from the exposed users.
- Download Rate (DR) is calculated as $DR = D/UV$, where D is the number of exposed users who download the recommended map.
- Entrance Rate (ER) is calculated as $ER = E/UV$, where E is the number of exposed users who enter the recommended map in LEGO@Cube.
- Conversion Rate (CR) is calculated as $CR = PU/UV$, where PU is the number of purchasing users.

- (2) **Evaluation metrics on Tgame and Ygame** include Conversion Rate (CR) as used in LEGO@Cube and Average Revenue Per User (ARPU) (i.e., $ARPU = R/UV$, where R is the total revenue and UV is the number of users exposed).

As an effort to quantifying the size of each experiment group without revealing the exact number of users exposed, we also give the Normalized User View (NUV). NUV is the number of users exposed in each experiment group divided by the number of users exposed in the group for M³Rec. Thus the NUV of M³Rec always equals one.

We report the results with the confidence level $\rho \geq 0.95$ in Tables 5, 6 and 7. We can observe that M³Rec significantly outperforms previously deployed competitors, in terms of all evaluation metrics that are designed by the operation team. This clearly suggests the great potential of M³Rec in online gaming.

5 RELATED WORK

In this section, we will elaborate on the relevant works which can be concluded into three main paradigms: *General Recommender Systems*, *Sequential Recommender Systems* and *Multi-task Recommender Systems*.

5.1 General Recommender Systems

Recommender Systems (RS) have become an essential tool for solving information overload problem [46]. RS not only assists users in searching for desirable targets but also helps e-commerce platforms promote their products and boost sales [1]. Traditional RS do not consider sequential behaviors and they typically rely on collaborative filtering methods (CF), especially matrix factorization (MF) [22], to utilize historical user-item interactions for recommendation. MF factorizes the user-item interaction matrix into two low-dimensional latent matrices while preserving the inherent information from original user-item interactions. MF has proven its ability of modeling user preferences and item properties in Netflix Prize Challenge [3]. Due to its effectiveness when handling

large-scale data [23], MF has been successfully deployed in the industry (e.g., Facebook, Amazon and Netflix [1, 22]). One of the most challenging issues in traditional recommender systems is the cold-start problem, where historical data is not available for new users or items [1]. In order to alleviate the cold-start problem, many works have incorporated additional context information, which is also called auxiliary data or side information (e.g., social network [26, 27], review text [12, 60], image [59], structural data [9, 25], and location [34]), into recommendation models. However, traditional recommender systems only consider user-item interactions. It is difficult to use general recommenders for sequential recommendation task directly, since user sequential behaviors should also be modeled [28].

5.2 Sequential Recommender Systems

The research of sequential recommender systems (SRS) has emerged recently, as many real-world applications have sequence based traits [35, 63].

The pioneering works for sequential recommender systems (SRS) utilize Markov Chain (MC) which views the three-way interactions in SRS as two components: one is the interaction between the user and the next item and the other is the sequential history between previous items and the next item [8, 49, 50, 56, 71]. The former is well studied in Matrix Factorization (MF) [22] and the later can be sequentially modeled by MC. Therefore, MC based methods adopt the ideas from both MF and MC. The drawback of MC based model is that the state space quickly becomes unmanageable when trying to include all possible sequences of user selections [16]. Another line of works extends MC based SRS using the idea of “translation”: the next item is viewed as the translation from previous item via the user [12, 13, 24]. The major advantage of these works is that they are much faster than other methods. There are other works using non-machine learning methods. For example, Migliorini et al. [37] deals with the production of sequences of recommendations for dynamic groups by considering the role of the context.

Hidasi et al. [16] firstly introduce Recurrent Neural Network (RNN) into sequential recommendation problem and proposed GRU4Rec which utilizes RNNs with a Gated Recurrent Unit (GRU) for SRS. Later, they extended GRU4Rec to exploit additional features (e.g., picture and text) by using parallel RNN architectures [17]. Due to the large performance gain of GRU4Rec over traditional methods, RNN based methods (including RNN, GRU and LSTM) have become prevalent in recent studies of SRS [6, 15, 20, 28, 33, 45, 52, 55, 58, 64, 65]. In addition to RNN, a few researchers explored the possibility of using other neural networks for SRS. Tuan and Phuong [57] harnessed 3D Convolutional Neural Network (CNN) and side information to enhance the accuracy of sequential recommendation. Wu et al. [66] investigated how to improve SRS with Graph Neural Network (GNN) and each sequence is then represented as the composition of the global preference and the current interest of that sequence using an attention network. Following Wu et al. [66], a few recent works explore the potential of GNN in SRS [41, 42, 68].

There are also some SRS considering the availability of user identity in each sequence. Due to the fact that the past and current user sequences can be simply concatenated to obtain longer sequence for the same user. Epure et al. [10] introduced the concept

of medium-term behavior in addition to the existing short-term and long-term behaviors in personalized SRS for news and combined them together to enhance recommendation on the top of MC. Quadrana et al. [44] argued that concatenating user sequences when user identity is available will not yield the best result and proposed a Hierarchical RNN model with cross-session information transfer. Inspired by the success of language modeling, Hu et al. [18] modeled the information of the user and items in a sequence as the context and used probabilistic classifier to identify the item to be recommended next. Liu et al. [32] noticed the user interests drift in a long user sequence is not well modeled by conventional models. Therefore, they designed a short-term attention/memory priority model as a remedy. Song et al. [53] modeled social influence in sequential social recommender with RNN and a graph-attention neural network.

As explained in Section 1, conventional SRS are single-sequence and single-task and hence they are not suitable for the multi-sequence and multi-task recommendation task in Tencent Games platform.

5.3 Multi-task Recommender Systems

Multi-task learning has been successfully deployed in several applications [70]. Multi-task learning aim is to leverage useful information contained in multiple related tasks to help improve the generalization performance of all the tasks.

As far as we know, multi-task learning has not been introduced to SRS before, but there are some efforts in using multi-task learning to improve other types of RS. Wang et al. [62] proposed OMTCF which models each user in online CF as an individual task. OMTCF not only update the weight vectors of the user (task) related to the current observed data, but also the weight vectors of some other users (tasks) according to a user interaction matrix. With the similar idea, Wang et al. [62] introduced a multi-task learning framework which learns multiple rating prediction models simultaneously (one for the active user and one for each of the related users). Chen et al. [7] designed a multi-task framework for music playlist recommendation, which can deal with three recommendation tasks (i.e., cold playlist recommendation, cold user recommendation and cold song recommendation) in parallel. Ni et al. [38] considered optimizing multiple search and recommendation tasks in e-commerce platform and learned universal user representations across multiple tasks for more effective personalization. Multi-task learning is also used in knowledge graph enhanced RS. For instance, knowledge graph completion task can be utilized to assist recommendation task [4, 61]. Moreover, the induction of explainable rules from knowledge graphs can be integrated with recommendation task. Ma et al. [36] and the two tasks complement each other in a multi-task framework.

6 CONCLUSION

In this paper, we study a new research problem which naturally arises from the recommendation scenario of online games. Using the ideas of GNN and multi-task learning, we propose a new method M^3Rec to fully utilize the complex information in the heterogeneous sequential recommendation scenario of online games.

Online evaluations in three games of Tencent Games platform illustrate the effectiveness of $M^3\text{Rec}$. In the future, we plan to enhance the interpretability of $M^3\text{Rec}$ so that we can better understand the recommendation results.

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